

Extra office
hours: Thurs 2-4pm

MAT 3141 - Review

Dec 4, 2012

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What we called "elementary divisors" should really be called "invariant factors".

Q What is the connection between the invariant factors (what we called elementary divisors) mentioned after Thm. 7.2.5 and those that appear in the Smith normal form?

A The invariant factors (elementary divisors) of $T \in \text{End}_k V$ in the sense of Thm 7.2.5 are those of the matrix $xI - A$, where A is a matrix of T in some basis, in the sense of Smith normal form.

- One can use this to compute the rational canonical form
- to get the basis in which an operator is in rational canonical form see Section 8.6

Example: Find a Jordan canonical form of

$$A = \begin{pmatrix} 2 & -1 & -1 \\ 1 & 2 & 0 \\ -1 & 0 & 2 \end{pmatrix}$$

$$\det(xI - A) = \begin{vmatrix} x-2 & 1 & 1 \\ -1 & x-2 & 0 \\ 1 & 0 & x-2 \end{vmatrix} = x^3 - 6x^2 + 12x - 8$$

2 is a root of ↗

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$$\begin{array}{r}
 x^2 - 4x + 4 \\
 x-2 \overline{) x^3 - 6x^2 + 12x - 8} \\
 \underline{x^3 - 2x^2} \\
 -4x^2 + 12x - 8 \\
 \underline{-4x^2 + 8x} \\
 4x - 8
 \end{array}$$

$$\begin{aligned}
 \therefore x^3 - 6x^2 + 12x - 8 \\
 = (x-2)(x^2 - 4x + 4) \\
 = (x-2)^3
 \end{aligned}$$

So ^{only} eigenvalue is $\lambda=2$, with mult 3.

Let's find $\dim E_2$.

$$2I - A = \begin{pmatrix} 0 & 1 & 1 \\ -1 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix} \sim \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{pmatrix} \Rightarrow \dim E_2 = 1$$

\therefore Jordan canonical form is

$$\begin{pmatrix} 2 & 1 & 0 \\ 0 & 2 & 1 \\ 0 & 0 & 2 \end{pmatrix}$$

Possibilities for Jordan canonical form:

<u>Size of matrix</u>	<u>Distinct eigenvalues w/ mult</u>	<u>JCF</u>
1x1	λ_1 (mult 1)	(λ_1)
2x2	λ_1, λ_2 (both mult 1)	$\begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{pmatrix}$
	λ_1 (x2)	$\begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_1 \end{pmatrix}$ $\begin{pmatrix} \lambda_1 & 1 \\ 0 & \lambda_1 \end{pmatrix}$ $\dim E_{\lambda_1} = 2$ $\dim E_{\lambda_1} = 1$
3x3	$\lambda_1, \lambda_2, \lambda_3$	$\begin{pmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ 0 & 0 & \lambda_3 \end{pmatrix}$
	λ_1 (x2), λ_2	$\begin{pmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_1 & 0 \\ 0 & 0 & \lambda_2 \end{pmatrix}$ $\begin{pmatrix} \lambda_1 & 1 & 0 \\ 0 & \lambda_1 & 0 \\ 0 & 0 & \lambda_2 \end{pmatrix}$ $\dim E_{\lambda_1} = 2$ $\dim E_{\lambda_1} = 1$
	λ_1 (x3)	$\begin{pmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_1 & 0 \\ 0 & 0 & \lambda_1 \end{pmatrix}$ $\begin{pmatrix} \lambda_1 & 1 & 0 \\ 0 & \lambda_1 & 0 \\ 0 & 0 & \lambda_1 \end{pmatrix}$ $\begin{pmatrix} \lambda_1 & 1 & 0 \\ 0 & \lambda_1 & 1 \\ 0 & 0 & \lambda_1 \end{pmatrix}$ $\dim E_{\lambda_1} = 3$ $\dim E_{\lambda_1} = 2$ $\dim E_{\lambda_1} = 1$

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Size of matrix (A)
4x4

Distinct eigenvalues

λ_1 (x4)

(other possibilities reduce to cases above)

JCF

$$\left(\begin{array}{ccc|ccc} \lambda_1 & 0 & 0 & 0 & 0 & 0 \\ 0 & \lambda_1 & 0 & 0 & 0 & 0 \\ 0 & 0 & \lambda_1 & 0 & 0 & 0 \\ 0 & 0 & 0 & \lambda_1 & 0 & 0 \end{array} \right)$$

$\dim E_{\lambda_1} = 4$

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$$\left(\begin{array}{ccc|cc} \lambda_1 & 1 & 0 & 0 & 0 \\ 0 & \lambda_1 & 0 & 0 & 0 \\ 0 & 0 & \lambda_1 & 0 & 0 \\ 0 & 0 & 0 & \lambda_1 & 0 \end{array} \right)$$

$\dim E_{\lambda_1} = 3$

$$\left(\begin{array}{ccc|ccc} \lambda_1 & 1 & 0 & 0 & 0 & 0 \\ 0 & \lambda_1 & 1 & 0 & 0 & 0 \\ 0 & 0 & \lambda_1 & 0 & 0 & 0 \\ 0 & 0 & 0 & \lambda_1 & 0 & 0 \end{array} \right)$$

$\dim E_{\lambda_1} = 2$

$\dim \text{Ker}(\lambda_1 I - A)^2 = 3$

$$\left(\begin{array}{ccc|cc} \lambda_1 & 1 & 0 & 0 & 0 \\ 0 & \lambda_1 & 0 & 0 & 0 \\ 0 & 0 & \lambda_1 & 1 & 0 \\ 0 & 0 & 0 & \lambda_1 & 1 \end{array} \right)$$

$\dim E_{\lambda_1} = 2$

$\dim \text{Ker}(\lambda_1 I - A)^2 = 4$

$$\left(\begin{array}{cccc} \lambda_1 & 1 & 0 & 0 \\ 0 & \lambda_1 & 1 & 0 \\ 0 & 0 & \lambda_1 & 1 \\ 0 & 0 & 0 & \lambda_1 \end{array} \right)$$

$\dim E_{\lambda_1} = 1$

Q What is the rational canonical form of

$$A = \begin{pmatrix} 2 & -1 & -1 \\ 1 & 2 & 0 \\ -1 & 0 & 2 \end{pmatrix}$$

A We found JCF $\begin{pmatrix} 2 & 1 & 0 \\ 0 & 2 & 1 \\ 0 & 0 & 2 \end{pmatrix}$. So $\min_A(x) = (x-2)^3$

$\therefore \min_A(x)$ is only invariant factor (elem. divisor)

(Recall $d_1(x) | d_2(x) | \dots | d_s(x) = \min_A(x)$ and $\sum \deg d_i = \text{size of matrix}$)

$$(x-2)^3 = x^3 - 6x^2 + 12x - 8$$

\therefore rational canan. form is

$$\begin{pmatrix} 0 & 0 & 8 \\ 1 & 0 & -12 \\ 0 & 1 & 6 \end{pmatrix} \quad \begin{pmatrix} 0 & 0 & 8 \\ 1 & 0 & -12 \\ 0 & 1 & 6 \end{pmatrix}$$

Other possible Ch 7/8 questions:

- use the structure theorem (abstract statement) to deduce something about a module of finite type over a ED
- find a basis of a col module (or of a span of some elements of a module)
- find a basis of a solution set to some equations with coeffs in a ED
- find a Smith normal form and the invariant factors (elementary divisors) of some matrix

[Q] Exercise 9.4.6(i). U, V f.d. v.s. $f \in U^*, g \in V^*$.

Show $\exists!$ linear form $f \otimes g : U \otimes_K V \rightarrow K$ s.t.

$$(f \otimes g)(u \otimes v) = f(u)g(v) \in U \times V.$$

[A] Define map $U \times V \rightarrow K$ by $(u, v) \mapsto f(u)g(v)$.

Exercise: Show this map is bilinear.

Then, by universal prop. of \otimes , we have unique map

$$U \otimes_K V \rightarrow K \text{ s.t. } u \otimes v \mapsto f(u)g(v).$$

This is our $f \otimes g$.

Q (ii) Show $U^* \otimes_k V^* \cong (U \otimes_k V)^*$.

A Exercise: Show $B: U^* \times V^* \rightarrow (U \otimes_k V)^*$, $(f, g) \mapsto f \otimes g$ is bilinear. So it induces map $U^* \otimes_k V^* \rightarrow (U \otimes_k V)^*$

Now show its image generates $(U \otimes_k V)^*$ as a v.s.

Let $\{u_1, \dots, u_m\}$, $\{v_1, \dots, v_n\}$ be bases of U and V .

$\therefore \{u_i \otimes v_j; 1 \leq i \leq m, 1 \leq j \leq n\}$ is a basis of $U \otimes_k V$

Let $\{f_1, \dots, f_m\}$, $\{g_1, \dots, g_n\}$ be dual bases of U^* and V^*

Then $(f_a \otimes g_b)(u_i \otimes v_j) = f_a(u_i) \otimes g_b(v_j) = \delta_{ai} \delta_{bj}$

$\therefore \{f_a \otimes g_b; 1 \leq a \leq m, 1 \leq b \leq n\}$ is basis of $(U \otimes_k V)^*$ dual to B , hence it generates $(U \otimes_k V)^*$. Since each $f_a \otimes g_b$ is in the image of B , we're done.

Finally,

$$\begin{aligned} \dim(U^* \otimes_k V^*) &= (\dim U^*)(\dim V^*) \\ &= (\dim U)(\dim V) \\ &= \dim(U \otimes_k V) \\ &= \dim(U \otimes_k V)^* \end{aligned}$$

\therefore the map $U^* \otimes_k V^* \rightarrow (U \otimes_k V)^*$ induced by B is a surjective linear map between v.s of the same dim. So it is an isomorphism.

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Q Exercise 10.1.4. V inn. prod. space w/ inn. prod \langle, \rangle .

(i) Verify that, for $u \in V$, the func. $f_u: V \rightarrow \mathbb{R}$ given by

$$f_u(v) = \langle u, v \rangle \quad \forall v \in V.$$

is in V^* and that the map $\varphi: V \rightarrow V^*$ given by $\varphi(u) = f_u \quad \forall u \in V$ is an isom of \mathbb{R} -v.s.

A Easy to check that $f_u \in V^*$ (i.e. is linear).

Easy to check that φ is linear.

Since $\dim V = \dim V^*$, suffices to show φ is injective.

Suppose $\varphi(u) = 0$ for some $u \in V$. So $f_u = 0$

$$\therefore \langle u, v \rangle = f_u(v) = 0 \quad \forall v \in V$$

$$\Rightarrow u = 0.$$

Q (ii). $B = \{u_1, \dots, u_n\}$ orthonormal basis of V . Show that

basis of V^* dual to B is $B^* = \{f_1, \dots, f_n\}$, where

$$f_i := \varphi(u_i) = f_{u_i} \quad \text{for } i = 1, \dots, n.$$

A We have $f_i(u_j) = f_{u_i}(u_j) = \langle u_i, u_j \rangle = \delta_{ij}$. \square