

MAT 1302B – Mathematical Methods II

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Winter 2015 – Lecture 1

Course webpage:

<http://mysite.science.uottawa.ca/asavag2/mat1302>

These are partial slides for following along in class. Full versions of these slides will be posted on the course website after the lecture.

Overview

Webpage: <http://mysite.science.uottawa.ca/asavag2/mat1302>

Keys to success:

- After each class, do the recommended exercises for that class **before the next lecture**
- Read the section in the text **before each lecture**
- Attend class and the DGDs

If you have difficulties:

- As soon as you have a difficulty, resolve it!
 - ▶ come to office hours
 - ▶ go to the help centre
 - ▶ ask the TA during the DGD
- The course will become very difficult if you fall behind

Note: DGDs begin week of January 19.

Taking notes

Partial slides will be posted before each class. Full slides will be posted after each class. Download a copy to your personal computer or USB flash drive in case the server goes down before an exam!

Video of each lecture will be made available for streaming online.

You should not try to write down everything presented in class (you won't have enough time and you can download the slides).

Instead, you should focuss on writing down the key ideas, important concepts, potential pitfalls, etc.

If you don't understand something at first, but then it clears up after further examples done in class, you should write yourself a note about that issue to remind yourself later.

What is linear algebra?

Algebra

-
-
-

Linear

- Geometric:
- Algebraic:

Linear algebra

Study of vectors, matrices, linear transformations and systems of linear equations

Linear geometry

Vectors and lines are linear



Planes are linear



(3-dimensional) space is linear

Linear equations

Question

What is a linear equation? Possible ideas:



Example

Example

Note: We will often use x_1, x_2, x_3, \dots instead of x, y, z .

Linear equations: Definition

What do the above examples have in common?

Definition (Linear Equation)

A **linear equation** in the variables x_1, \dots, x_n is an equation that can be written in the form

$$a_1x_1 + a_2x_2 + \dots + a_nx_n = b$$

where $a_1, a_2, \dots, a_n, b \in \mathbb{R}$ are the coefficients and n can be any positive integer.

Linear equations: Examples

Example 1

$$-x_1 + 5x_2 - 3x_3 = 1$$

Example 2

$$2x_1 - 5 = 3x_2 + x_1 - 8$$

Example 3

$$\sqrt{2}(x_1 - x_2) = \pi(5 - x_1)$$

Linear equations: Examples

Example 4

$$(2x_1 - 1)(3 - x_2) = 0$$

is _____

Example 5

$$x_1^2 + x_2 = 3$$

is _____

Linear equations: Examples

Example 6

$$\sqrt{x_1} + x_2 = 0$$

is _____

Example 7

$$x_1^2 - 1 = (x_1 + 1)(x_1 - 1) \quad (1)$$

Recall: An equation is linear if it **can be** written in the form

$$a_1x_1 + \cdots + a_nx_n = b.$$

Systems of linear equations

Definition (System of linear equations)

A **system of linear equations** (or **linear system**) is a collection of one or more linear equations involving the same variables.

Example

$$\begin{array}{rclcl} 3x_1 & - & 2x_2 & + & x_3 & = & 4 \\ & & 5x_2 & - & x_3 & = & -1 \end{array}$$

Definition (Solution of a linear system)

A **solution** of the system is a list (s_1, \dots, s_n) of numbers that makes each equation a true statement when the values s_1, \dots, s_n are substituted for x_1, \dots, x_n (in that order).

Systems of linear equations: Example

Example

Recall our example

$$\begin{aligned}3x_1 - 2x_2 + x_3 &= 4 \\5x_2 - x_3 &= -1\end{aligned}$$

$(1, 0, 1)$, i.e. $x_1 = 1$, $x_2 = 0$, $x_3 = 1$, is a solution of this system since substitution gives

$$\begin{aligned}3(1) - 2(0) + (1) &= 4 \quad \checkmark \\5(0) - (1) &= -1 \quad \checkmark\end{aligned}$$

$(1, 1, 3)$, i.e. $x_1 = 1$, $x_2 = 1$, $x_3 = 3$, is **not** a solution since substitution gives

$$\begin{aligned}3(1) - 2(1) + (3) &= 4 \quad \checkmark \\5(1) - (3) &= -1 \quad \times\end{aligned}$$

Solution sets

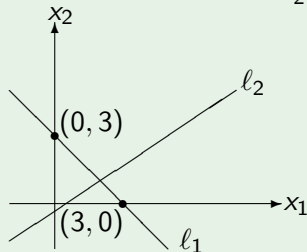
Definition (Solution set)

The **solution set** of a linear system is the set of **all** possible solutions of the system.

Example 1

$$l_1 : x_1 + x_2 = 3$$

$$l_2 : 2x_1 - 3x_2 = 1$$



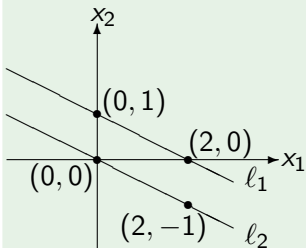
- The pair of numbers (s_1, s_2) satisfies both equations iff it lies on both lines.
- The solution set

Solution sets

Example 2

$$l_1 : x_1 + 2x_2 = 2$$

$$l_2 : -x_1 - 2x_2 = 0$$



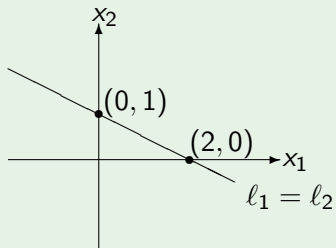
-
- The system has _____
- The solution set is _____

Solution sets

Example 3

$$l_1 : x_1 + 2x_2 = 2$$

$$l_2 : 2x_1 + 4x_2 = 4$$



There are _____

Possible solution sets

Question

What types of solutions sets can systems of linear equations have?

Answer

A system of linear equations has either

- | | |
|-----------------------------|-------------------------------|
| ① No solution | system is inconsistent |
| ② Exactly one solution | } system is consistent |
| ③ Infinitely many solutions | |

Note: This is special to **linear** systems.

Example:

Matrix notation

In order to simplify calculations, we often encode the info of a linear system in a **matrix**.

Example

For the system

$$\begin{array}{rccccrcr} 2x_1 & - & x_2 & - & x_3 & + & x_4 & = & 7 \\ & & x_2 & + & x_3 & + & 2x_4 & = & -8 \\ 5x_1 & & & - & 3x_3 & - & x_4 & = & 0 \end{array}$$

we have two matrices:

coefficient matrix

$$\begin{bmatrix} 2 & -1 & -1 & 1 \\ 0 & 1 & 1 & 2 \\ 5 & 0 & -3 & -1 \end{bmatrix}$$

augmented matrix

$$\left[\begin{array}{cccc|c} 2 & -1 & -1 & 1 & 7 \\ 0 & 1 & 1 & 2 & -8 \\ 5 & 0 & -3 & -1 & 0 \end{array} \right]$$

Matrix sizes

In our previous example:

coefficient matrix

$$\begin{bmatrix} 2 & -1 & -1 & 1 \\ 0 & 1 & 1 & 2 \\ 5 & 0 & -3 & -1 \end{bmatrix}$$

augmented matrix

$$\left[\begin{array}{cccc|c} 2 & -1 & -1 & 1 & 7 \\ 0 & 1 & 1 & 2 & -8 \\ 5 & 0 & -3 & -1 & 0 \end{array} \right]$$

The coefficient matrix has size 3×4 and the augmented matrix has size 3×5 .

Definition

A matrix has size $m \times n$ if it has m rows and n columns.

Note: Sometimes (for instance, in the text) the vertical bar in the augmented matrix is omitted.

Question: What type of linear system is completely trivial to solve?

Answer:

Example

Moral

- Ideally, we would like to manipulate a system to turn it into an easy system like this.
- This won't always be possible, but we'll come close.

Example

Let's solve a particular linear system. In each step, we'll also write the augmented matrix.

$$\begin{array}{rclcrcl} 2x_1 & + & 4x_2 & - & 2x_3 & = & -6 \\ & & x_2 & + & 3x_3 & = & 6 \\ 3x_1 & + & 4x_2 & - & x_3 & = & -5 \end{array} \quad \left[\begin{array}{ccc|c} 2 & 4 & -2 & -6 \\ 0 & 1 & 3 & 6 \\ 3 & 4 & -1 & -5 \end{array} \right]$$

1

$$\begin{array}{rclcrcl} x_1 & + & 2x_2 & - & 1x_3 & = & -3 \\ & & x_2 & + & 3x_3 & = & 6 \\ 3x_1 & + & 4x_2 & - & x_3 & = & -5 \end{array} \quad \left[\begin{array}{ccc|c} 1 & 2 & -1 & -3 \\ 0 & 1 & 3 & 6 \\ 3 & 4 & -1 & -5 \end{array} \right]$$

2

Example (cont.)

2

$$\begin{array}{rclcrcl} x_1 & + & 2x_2 & - & 1x_3 & = & -3 \\ & & x_2 & + & 3x_3 & = & 6 \\ & & -2x_2 & + & 2x_3 & = & 4 \end{array} \quad \left[\begin{array}{ccc|c} 1 & 2 & -1 & -3 \\ 0 & 1 & 3 & 6 \\ 0 & -2 & 2 & 4 \end{array} \right]$$

3

$$\begin{array}{rclcrcl} x_1 & + & 2x_2 & - & 1x_3 & = & -3 \\ & & x_2 & + & 3x_3 & = & 6 \\ & & & & 8x_3 & = & 16 \end{array} \quad \left[\begin{array}{ccc|c} 1 & 2 & -1 & -3 \\ 0 & 1 & 3 & 6 \\ 0 & 0 & 8 & 16 \end{array} \right]$$

The system is now in _____

4

$$\begin{array}{rclcrcl} x_1 & + & 2x_2 & - & 1x_3 & = & -3 \\ & & x_2 & + & 3x_3 & = & 6 \\ & & & & x_3 & = & 2 \end{array} \quad \left[\begin{array}{ccc|c} 1 & 2 & -1 & -3 \\ 0 & 1 & 3 & 6 \\ 0 & 0 & 1 & 2 \end{array} \right]$$

Example (cont.)

5 (a)

(b)

$$\begin{array}{rcl} x_1 + 2x_2 & = & -1 \\ & x_2 & = 0 \\ & x_3 & = 2 \end{array} \quad \left[\begin{array}{ccc|c} 1 & 2 & 0 & -1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 2 \end{array} \right]$$

6

$$\begin{array}{rcl} x_1 & = & -1 \\ & x_2 & = 0 \\ & x_3 & = 2 \end{array} \quad \left[\begin{array}{ccc|c} 1 & 0 & 0 & -1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 2 \end{array} \right]$$

Solution:

Important: Check your answer!

Question

How can we check that our solution is correct? Maybe we made some mistakes along the way!

Answer

Example

Elementary row operations

When solving linear systems, we will use three basic row operations.

Elementary row operations

- 1 **Replacement:** Replace one row by the sum of itself and a multiple of another row (i.e. add a multiple of one row to another row).
- 2 **Interchange:** Interchange two rows.
- 3 **Scale:** Multiply all entries in a row by a nonzero constant.

Definition

Two matrices are **row equivalent** if one can be obtained from the other by a sequence of elementary row operations.

Row equivalence: Example

Example

We see from our previous example that the matrices

$$\left[\begin{array}{ccc|c} 2 & 4 & -2 & -6 \\ 0 & 1 & 3 & 6 \\ 3 & 4 & -1 & -5 \end{array} \right] \quad \text{and} \quad \left[\begin{array}{ccc|c} 1 & 0 & 0 & -1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 2 \end{array} \right]$$

are row equivalent since we obtained the second from the first via row operations.

Row operations: reversibility

Note: All the row operations are reversible.

Examples

- ① **Operation:** Add cR_1 to R_2 .
Reverse:
- ② **Operation:** Interchange R_2 and R_3 .
Reverse:
- ③ **Operation:** Multiply R_2 by c , $c \neq 0$.
Reverse:

Row equivalence and solution sets

- If a matrix A is obtained from a matrix B by row operations, then any solution of the system corresponding to A is a solution of the system corresponding to B .
- Since A can also be obtained from B by row operations, any solution of the system corresponding to B is a solution of the system corresponding to A .

Theorem

If the augmented matrices of two linear systems (LS's) are row equivalent, then the two systems have the same solution set.

In our example, we solved the LS by finding a row equivalent one which was simpler and allowed us to read off the solution.

Another Example

Determine if the following system is consistent:

$$\begin{array}{rclclcl} & & -2x_2 & + & x_3 & = & 2 \\ -x_1 & + & 2x_2 & + & 3x_3 & = & -1 \\ -2x_1 & + & 6x_2 & + & 5x_3 & = & -1 \end{array}$$

Solution: The augmented matrix is

$$\left[\begin{array}{ccc|c} 0 & -2 & 1 & 2 \\ -1 & 2 & 3 & -1 \\ -2 & 6 & 5 & -1 \end{array} \right]$$

We use row operations to get it to triangular form.

Another Example (cont.)

$$\begin{aligned} & \left[\begin{array}{ccc|c} 0 & -2 & 1 & 2 \\ -1 & 2 & 3 & -1 \\ -2 & 6 & 5 & -1 \end{array} \right] & \longrightarrow & \left[\begin{array}{ccc|c} -1 & 2 & 3 & -1 \\ 0 & -2 & 1 & 2 \\ -2 & 6 & 5 & -1 \end{array} \right] \\ & \longrightarrow & \left[\begin{array}{ccc|c} 1 & -2 & -3 & 1 \\ 0 & -2 & 1 & 2 \\ -2 & 6 & 5 & -1 \end{array} \right] & \longrightarrow & \left[\begin{array}{ccc|c} 1 & -2 & -3 & 1 \\ 0 & -2 & 1 & 2 \\ 0 & 2 & -1 & 1 \end{array} \right] \\ & \longrightarrow & \left[\begin{array}{ccc|c} 1 & -2 & -3 & 1 \\ 0 & 1 & \frac{-1}{2} & -1 \\ 0 & 2 & -1 & 1 \end{array} \right] & \longrightarrow & \left[\begin{array}{ccc|c} 1 & -2 & -3 & 1 \\ 0 & 1 & \frac{-1}{2} & -1 \\ 0 & 0 & 0 & 3 \end{array} \right] \end{aligned}$$

Back to equation notation:

$$\begin{aligned} x_1 - 2x_2 - 3x_3 &= 1 \\ x_2 - \frac{1}{2}x_3 &= -1 \\ 0 &= 3 \end{aligned}$$

-
- The system is _____.

Recap

Before next class, you should:

- Go over webpage (syllabus, DGDs, grading, etc.).
- Read “Lecture 0” (background on sets, notation, etc.).
- Do recommended exercises.
- Read Sections WILA, SSLE, and RREF of the text.

Next time

- We will develop a systematic procedure for solving systems of equations.
- Our procedure will allow us to solve **any** system of equations (or determine that it has no solutions).